INTRODUCTION

In this session, makers are introduced to programming servo motors with the Micro:bit.

The servo motor can be a neat addition to the options for coding the Micro:bit, in preparation for the Cyber Arcade projects they’ll be working on in the following weeks.

ESSENTIAL QUESTIONS

• What is a servo motor and how can I control it with code?
• How do artists, engineers, and makers solve problems when they’re working?

LEARNING OUTCOMES

1. Learn how to use code to program a servo motor.
2. Engage in project-based learning through problem-solving and troubleshooting by creating a game using a Micro:bit and code.
## VOCABULARY

**Servo motor**: Motor that can be programmed with an electrical signal to move to a specific position

**Servo mounting horn**: Attaches to the servo to allow other objects to be connected to the servo (e.g., a wheel or an arm)

**User**: Person playing and interacting with the game

**User interface (UI)**: Physical and digital design of how the user interacts with the game

**User experience (UX)**: How natural and enjoyable the experience is

**Troubleshooting**: Using resources to solve issues as they arise
MATERIALS LIST

EACH PAIR OF MAKERS NEEDS:

- Micro:bit microcontroller
- AAA batteries (2)
- External battery pack
- Alligator-to-pin wires (3)
- Servo motor with servo horns
- Laptop with internet connection
- USB to micro-USB cord
- USB flash drive
- Notebook
- Mini screwdriver
TEACHER PREP WORK

1. Prepare the projector and make sure the internet is working.
2. Preload the slideshow and videos to save time.
3. Prepare an example of a servo with code from Steps 2 and 3 (optional).
4. Attach servo mounting horns to servo motors using a small screwdriver.
5. Print the Troubleshooting Tips at the end of the lesson and post in the classroom.

FACILITATION TIPS

Tinkering with electronics: Tinkering with electrical connections on a servo can be a bit tricky and won’t work if things aren’t securely connected. If students get frustrated, encourage them to check the color coding of the wires throughout the process and to also use the Troubleshooting Tips. They can use painter’s tape or other non-permanent ways of securing connections.

Materials management: It’s up to you as the educator to decide what works best for your class. You can portion out maker materials into paper trays for each table, or have a dedicated area where makers can access materials freely as needed.

Collaboration: Let smaller issues work themselves out. Record specific positive examples that you can share with makers in the moment or at the end of the project. These examples provide models for all learners.

Frustration: When frustration levels aren’t high, let learners figure it out or keep facilitation low touch by asking a question and walking away. When frustration levels are high, intervene more directly to help makers find some success.

Circulate among the makers and monitor for both collaboration and frustration.

ADDITIONAL RESOURCES

Behind the MakeCode Hardware:
- Servo Motors with Micro:bit
- Driving a Servo with the Micro:bit
- Connecting a Servo Motor to the Micro:bit
INTRODUCTION TO SERVOS

**STEP 1**

*Introduce the servo motor.*

![Servo Diagram]

Ask makers:
- What is a motor? (*A: Device that converts electrical energy into rotating mechanical energy.*)
- What kinds of devices have motors in them? (Students should brainstorm.)

Give each group of makers a servo motor with a servo horn attached. Makers will draw and list parts they notice in their notebook.

**Note:** Advise makers to handle gently and to not force the turning of the arm, as it could break.

Ask makers to:
- Study the servo parts closely.
- Describe what they see/notice.

The parts to emphasize are: the 3 colored wires, gears, plastic arms, and the fact that the arm turns.

**STEP 2**

*Program the servo motor.*

Show makers this short video that demonstrates Micro:bit buttons A/B controlling a moving servo motor.

*Servo Attached to Micro:bit* on YouTube, uploaded by Teach with ICT, 6/25/2018
EXPLAIN

We can program a servo to turn a specific amount by connecting it to the Micro:bit board and using special servo coding blocks. First, let’s work with the code in the simulator. Then, we’ll upload it to the board and connect the servo to the board.

DEMONSTRATE AND HAVE MAKERS FOLLOW ALONG:

1. Go to the MakeCode editor URL (makecode.microbit.org) and open a new project.

2. In the blocks menu, click on Advanced and then scroll down to click on Extensions.

3. This will take you to a new page. Click on “servo A micro-servo library”. This will add the additional blocks we need to program the servo.

4. Click and drag over a when button A is pressed from the Inputs menu.

5. Drag over a pause block from the Basic menu and nest it in the first block.

6. Change the pause time to be 1 sec (or 1000 ms).

7. Notice there’s a new Servos block menu. Click and drag over a set servo
8. Click on the number 90 within the block and change it to be the number 1. Then you’ll notice a servo appear in the simulator.

9. Repeat the `pause` and `set servo` blocks by duplicating or dragging over new blocks. This time, change the value in the `set servo` block to be 180. Click on `button A` in the simulator, and you’ll notice that the servo will move to the opposite side.

10. Repeat Steps 8 and 9 two more times. You’ll have a series of blocks that look like the blocks below. Again, click on `Button A` in the simulator and you should see the servo arm move back and forth twice.

11. Name your file with a unique name and save the file to the USB flash drive. Connect the Micro:bit with the USB cord.
Click and drag the file on to the Micro:bit to upload.

**Note:** Leave the Micro:bit connected to the laptop for the next step.

**STEP 3**

**Connect the servo motor.**

Once makers have successfully programmed a servo in the simulator and uploaded the code to the Micro:bit, it’s time to connect the physical servo to the board. The Micro:bit should still be connected to the laptop.

Give each group 3 alligator-to-pin wires, one servo, and a battery pack.

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**EXPLAIN**

Now that we’ve tested our code and uploaded it to the Micro:bit, we’ll connect the servo.

**DEMONSTRATE AND HAVE MAKERS FOLLOW ALONG:**

1. In order for the servo to get the code, we need to connect 3 of the alligator-to-pin wires to the GND, 3V, and PIN 0 terminals on the Micro:bit board using the alligator side of the wire.

2. Next, notice on the servo there are 3 colored wires: black, red, and orange. These wires are important to keep track of. The brown wire is the ground wire (GND) or the (–) terminal and the red wire is the 3V or (+) terminal. These help to deliver electricity and power to the servo. The orange wire is the signal wire, or the wire that actually delivers the code from the programmed pin on the Micro:bit to the servo.
3. Connect your servo wires to the Micro:bit board following the table below. If you can match the colors of the servo motor, great! If not, the colors of the alligator-to-pin wires don’t actually matter—it’s just helpful to use the same colors so we can easily track where the wires are going.

<table>
<thead>
<tr>
<th>GND</th>
<th>Brown</th>
</tr>
</thead>
<tbody>
<tr>
<td>3V</td>
<td>Red</td>
</tr>
<tr>
<td>PIN</td>
<td>Yellow</td>
</tr>
</tbody>
</table>

4. Once you think you have the connections right, try pressing Button A and check if the servo is moving or not. You’ll hear a mechanical rotating sound if the servo is working. If your servo doesn’t already have a plastic mounted “horn” piece, then use a mini screwdriver to attach one so that it’s easier to see the movement.

5. If the servo works as displayed on the computer simulator, you can disconnect the Micro:bit and connect it to a battery pack.

6. If the servo isn’t moving, check your wiring to see if the connections are right (Steps 2 and 3). If the servo is still not moving from 0 to 180 degrees, then check the code on the screen.
STEP 4

Further explore programming the servo.

Once makers have successfully programmed and connected a servo, have them go back and tinker with the code (e.g., change inputs, add displays, move a different amount of degrees, etc.). Remind them that they’ll need to plug their Micro:bit back into their computer.

STEP 5

Clean up.

Makers will:

- Put away technology and make sure laptops are charging.
- Return tools and materials that can be used again to the right place.
- Clear tables of garbage and recycling.
## Troubleshooting Tips

<table>
<thead>
<tr>
<th>Problem</th>
<th>Solution</th>
</tr>
</thead>
</table>
| **The servo isn’t moving or responding.** | **Alligator-to-pin wires**  
• Check to see that the wires are properly connected to the servo (GND to brown, 3V to red, and Pin to orange).  
• Make sure alligator clips are secure on the correct pins and are touching the metallic parts. Try extending from the board with a paper fastener.  
• Try switching out the alligator clips for new ones.  
| **Power**  
• The servo might not be getting enough power from the battery pack. Try powering the Micro:bit using the USB to the laptop. If it works, replace the batteries or the battery pack and try again.  
• Try pressing the reset button on the Micro:bit. |
| **The servo is making some sound but not rotating.** | **Bugs in the code**  
• Read through the code.  
• Check to make sure there’s a short pause block in the code before and after every turn. The servo cannot move without a pause before and after moving.  
• The servo gears could be burnt out or broken. Try replacing the servo. |
| **The servo isn’t turning the amount we thought it should.** | **Servo type**  
• Try connecting a different servo and try again.  
• Servo gears could be uncalibrated or broken. Replace the servo and try again. |
<table>
<thead>
<tr>
<th>Issue</th>
<th>Possible Causes</th>
</tr>
</thead>
<tbody>
<tr>
<td>The LED on the Micro:bit isn’t flashing when we click Upload.</td>
<td><strong>Bad cable or port</strong>&lt;br&gt;• If the Micro:bit isn’t showing up in the computer menu, try a different cable.&lt;br&gt;• Try a different USB port on the laptop.</td>
</tr>
<tr>
<td>Our code isn’t uploading correctly to the board. The board feels hotter than usual.</td>
<td><strong>Burnt board</strong>&lt;br&gt;• Try pressing the reset button on the board.&lt;br&gt;• Try uploading to a new Micro:bit board.&lt;br&gt;• Check to see if there’s conductive material touching the board. It could be causing a short circuit.</td>
</tr>
<tr>
<td>The board isn’t turning on when connected to the battery pack.</td>
<td><strong>Battery</strong>&lt;br&gt;• Test the batteries to see if they’re charged.&lt;br&gt;• Check to see if the batteries are flipped.</td>
</tr>
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<td>The LED on the Micro:bit isn’t flashing when we click Upload.</td>
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</tr>
<tr>
<td>The connections won’t stay in place.</td>
<td><strong>Alligator clips</strong>&lt;br&gt;• Use painters tape to hold the alligator clips in place.&lt;br&gt;• Try using foil or paper fasteners to extend the metal parts of the board (Pin, GND, 3V).</td>
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</table>
TROUBLESHOOTING TIPS

Print and use the empty rows to fill in with other problems and solutions that can be shared.

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